

Recruiting pupils for Aeromodelling

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Recruiting pupils for Aeromodelling

- Why work with young talents ?
- New opportunities in Germany - School clubs
- Model building and Flight training
 - Indoor flying as training method
 - appropriate model designs
 - results of the training method
- Practical application of the teaching material in physics
 - movement patterns (steady motion, uniformly accelerated motion)
 - cruise flight and take-off process
 - efficiency of the drive system
- summary

Recruiting pupils for Aeromodelling

- shortage of young members
 - exists in most clubs
 - is not only a cosmetic problem
- without young members in a club
 - there is the risk of ageing
 - it might get unguided
 - sooner or later it will fall apart

Recruiting pupils for Aeromodelling

Analysis in 2000 → 2010:

- the former propaganda has lost its effectiveness: newspaper articles, homepage, club presentation events with model building at events (e.g. airport festival)



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A new attempt: Working groups in schools

- GanzTagsAngebot (GTA) = schooling
 - after three trial lessons: duty to visit the working group for a half year
 - presence control like in the classroom
 - short progress reports 4 times per school year
 - best possibility for contact with students
- for example: Modellflug Club Rossendorf e.V.
 - program runs in a nearby located High School in Dresden since Sept 2009
 - at start: 2 students of the 5th grade participated
 - in present SY 2015/16: in total 16 students participate
(4x5th, 6x6th, 3x8th, 1x9th grade)
 - from those participants: 5 became members of our club

Schooling-Program of the first years

Styropor glider → Ba_glider (Opitec) → Free Flight model (Aeronaut) → Motor glider



- several students built a motor glider
→ that worked well
- training with the mot gliders on our
flying field → that did not work well

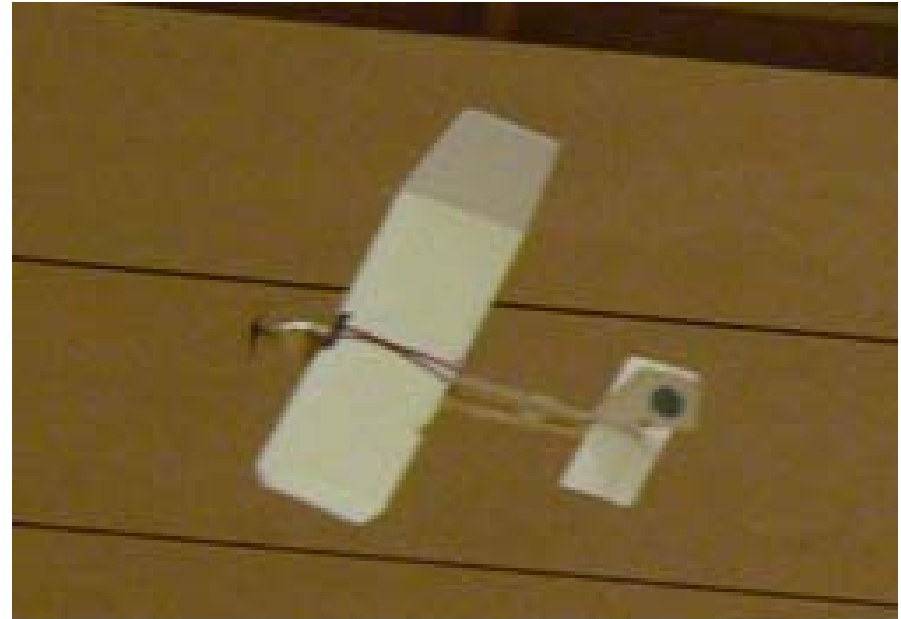
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Schooling-Experiences of the first years

- building program okay, but flight training did not worked out:
 - on the GTA-day the weather was not always good
 - a continuous training was not possible
- low efficiency: only small progress in control quality during a long period of time:

$$\eta = \frac{\text{achieved quality of control}}{\text{invested time}} \ll 1$$

alternative: indoor flying as training method?



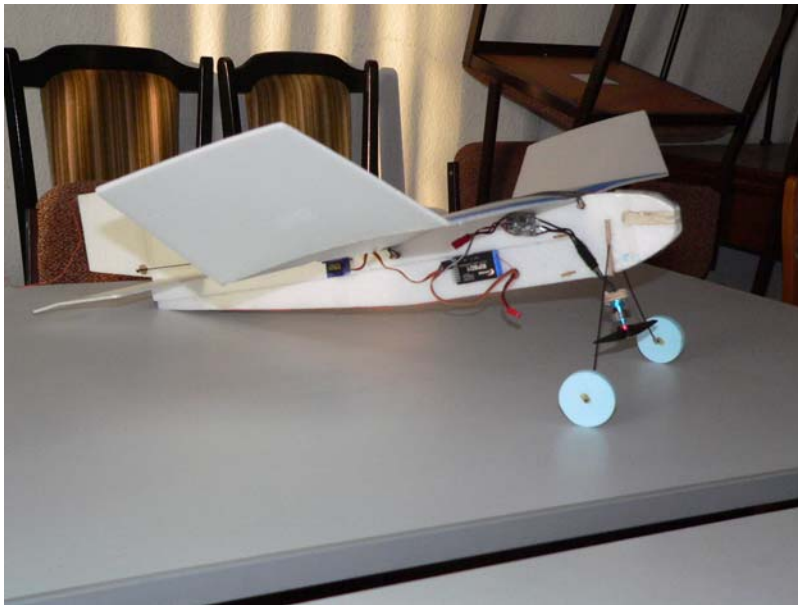
- not a teaching in indoor aerobatics flight (F3P) !!
- A: flight training immediately after school lessons in gym
- D: limited flight space
- Q: indoor flying nevertheless a workable solution?

alternative: indoor flying as training method?

- required attributes of the model
 - slow flying □ reaction time of the teacher !?
 - robust toward impacts on wall and on ground
 - docile controllable and comparable with motor glider flight properties
 - low costs in building, material also from do-it-yourself-market
- Realisation
 - airfoil curved surface like Gö417a: $f_{max} = 6\%$, $c_{amax} = 1$
@ $Re=40000$, $\Lambda = \infty$
 - lightweight construction by using EPP and Styropor
 - no traction operation → pusher configuration

alternative: indoor flying as training method?

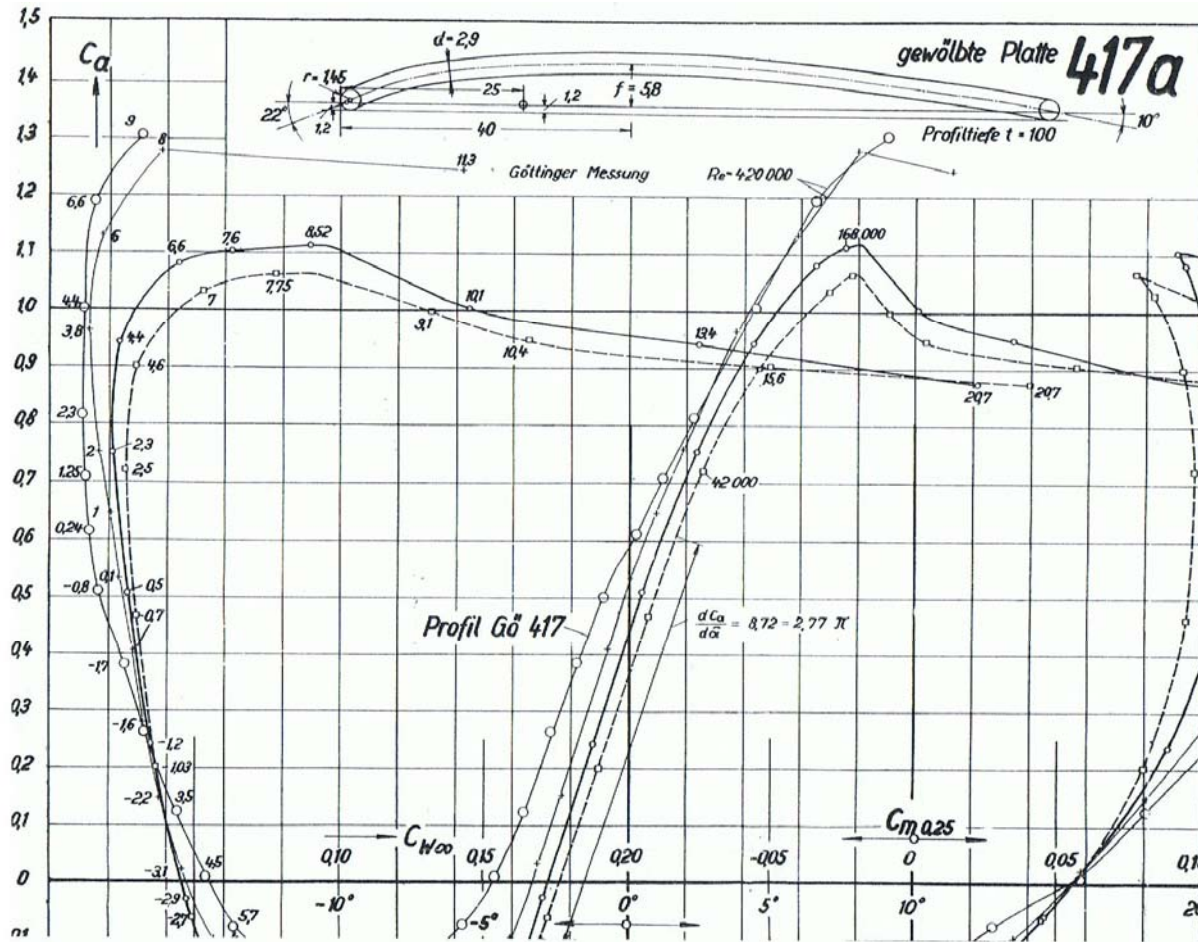
traction propulsion causes damages on prop or/and motor or model



→ the drive must be protected by using pusher propulsion!!

slow speed – how to achieve?

Estimation v_{min}



The polar curves are measured down to $Re = 42000$;

in comparison:

$$Re = \rho \cdot v \cdot l$$

$$= 200\text{mm} \cdot 5\text{m/s} \cdot 70$$

$$= 70000 > 42000$$

$$v_{min} = \sqrt{\frac{\text{mass} \cdot g}{2 \cdot P \cdot AF \cdot c_{amax}}}$$

$$C_{amax} = 0,8;$$

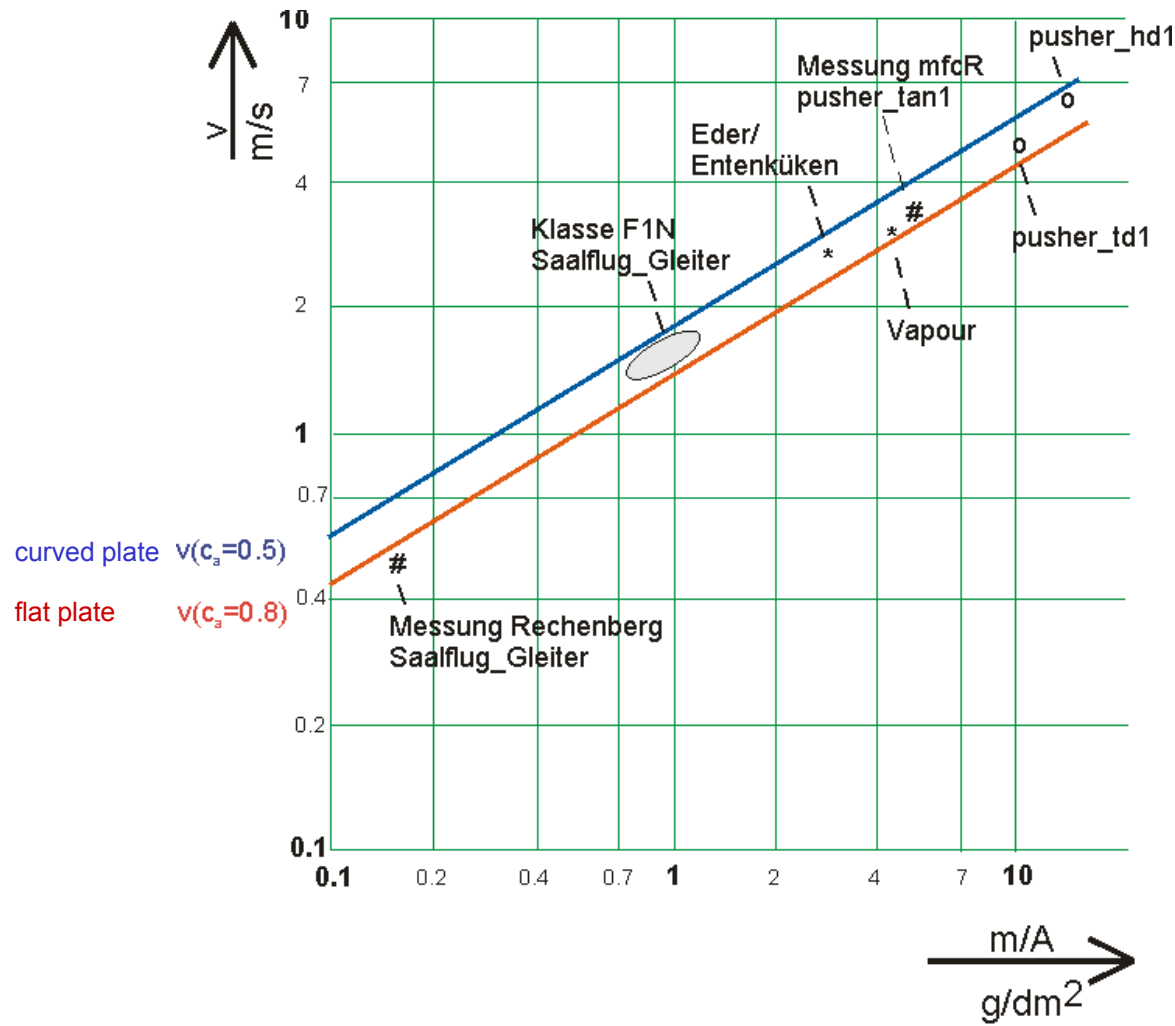
$$m = 170\text{gr};$$

$$AF = 16,4\text{qdm}$$

$$\rightarrow v_{min} = 4,5\text{m/s}$$

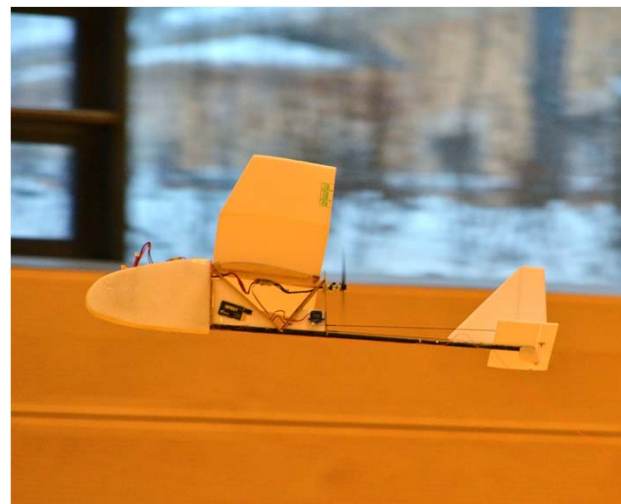
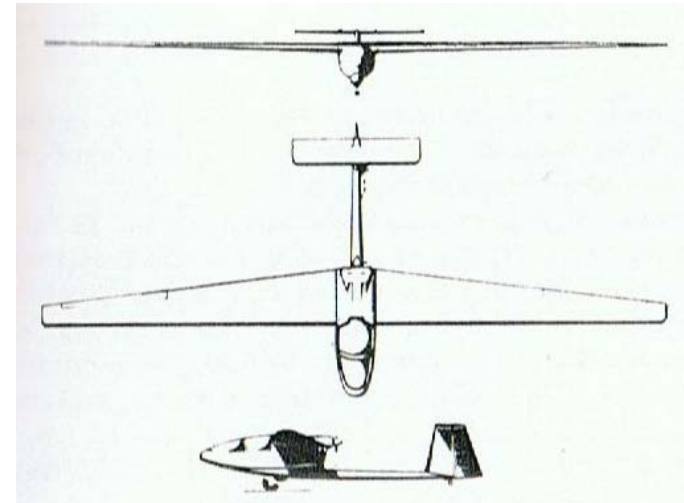
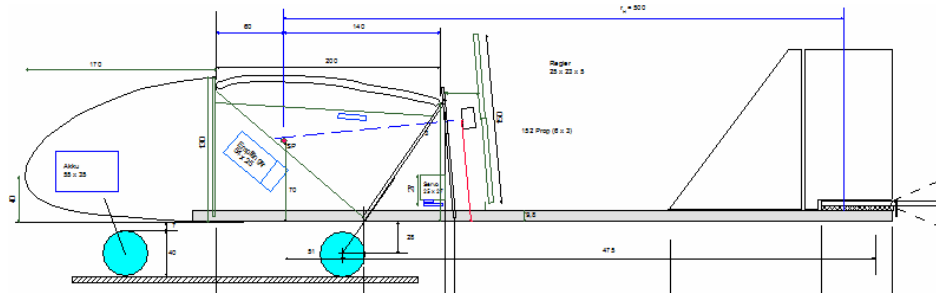
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classification v_{\min} versus mass/A



suitable pusher propulsion configurations:

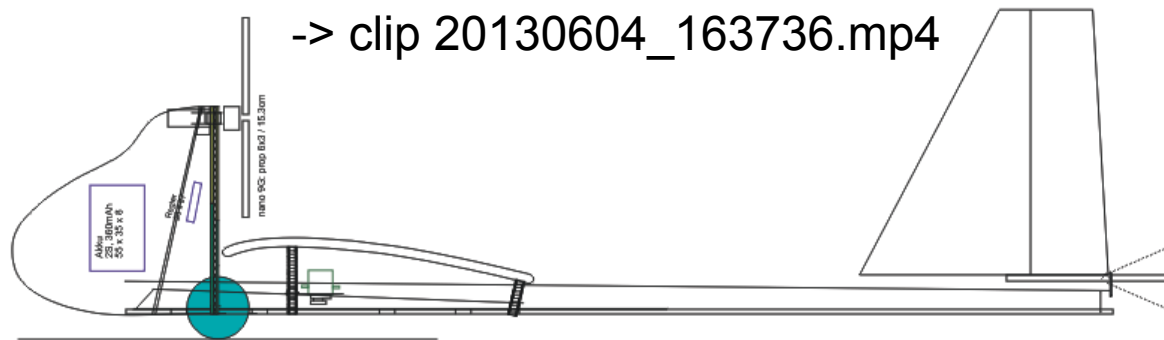
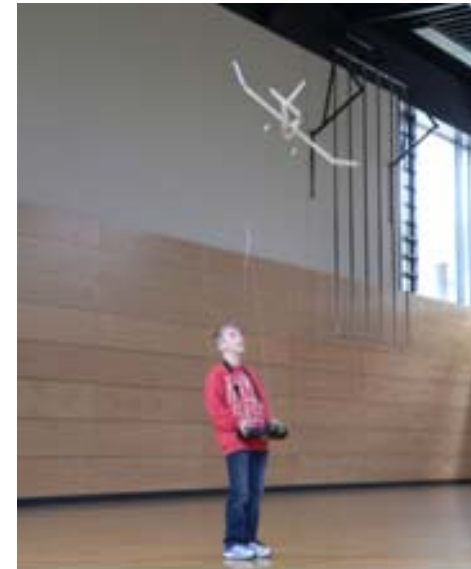
- inspired by the motor glider OGAR/CZ



A: prop and motor are protected, the hall's walls will spared; docile controllable;
D: mass = 220g
 $m/A = 13,5g/dm^2$
 $\rightarrow v \approx 6m/s$ too high!

suitable pusher propulsion configurations:

- bringing forward the motor behind the nose → low wing monoplane

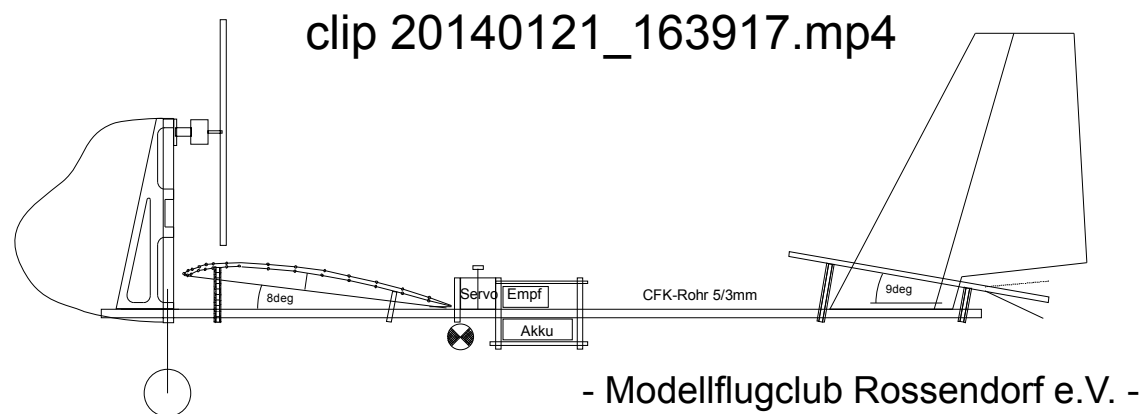
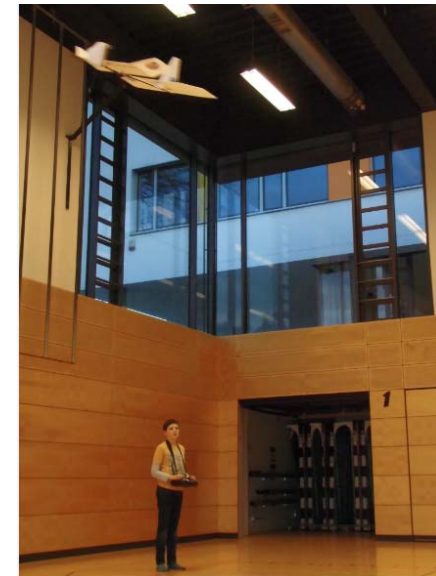
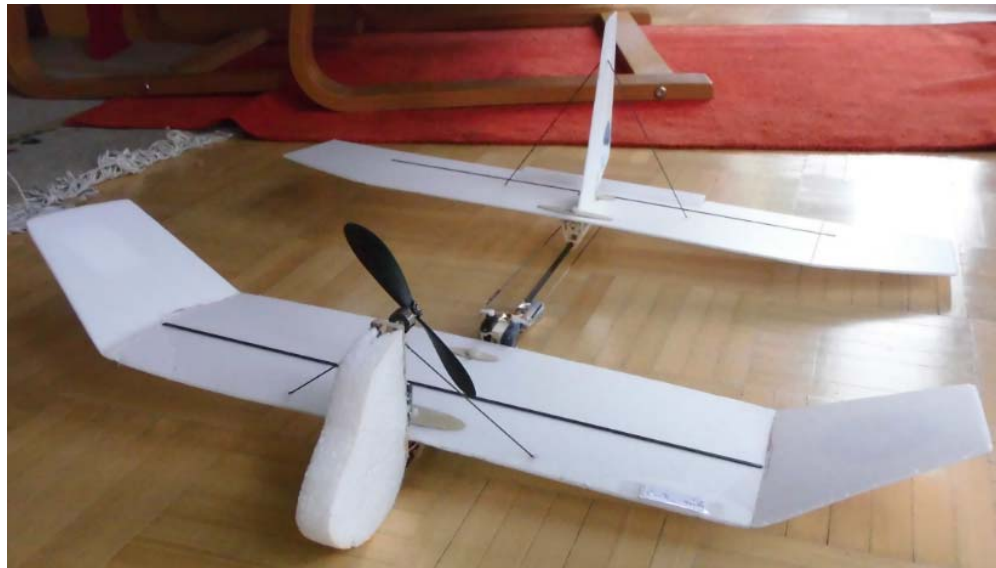


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A: $m = 170g$
 $m/A = 10,6g/dm^2$
-> $v \approx 4,2m/s$ good!
model still robust and docile controllable
D: fuselage's assembly a little bit complicated

geeignete pusher-Varianten:

- Reduction of m/A by enlargement the elevator's area (\rightarrow tandem-config)



A: mass = 120g
 $m/A = 7\text{g/dm}^2$
 $\rightarrow v \approx 3,5\text{m/s}$ – better !
 assembling very simple,
 modell still robust and
 docile controllable
 D: not found

Is indoor flying usable for RC-training?

Answer: **YES!** For example:

- 4 School-pupils took part at the end of the 5th grad in a model flyer camp
- after 2h practising time 3 of them were able to control motor gliders with span of 2 ... 3m
- also they could take part on the compet/electric class at the end of week



-> beginner training via Indoor flying is worth doing!!

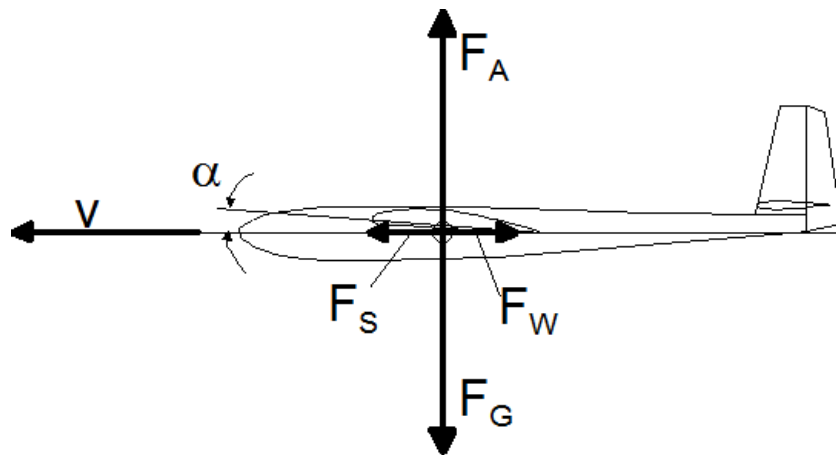
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Linking to School Physics

- model in flight are moved bodies
- take-off process:
 - uniformly accelerated motion
 - $v \neq \text{const}$ (increase)
- cruising flight:
 - steady movement
 - $v = \text{const}$

Linking to School Physics

- Cruising flight: $v = \text{const}$,
- measurement: time-acquisition over path marks with the help of pupils

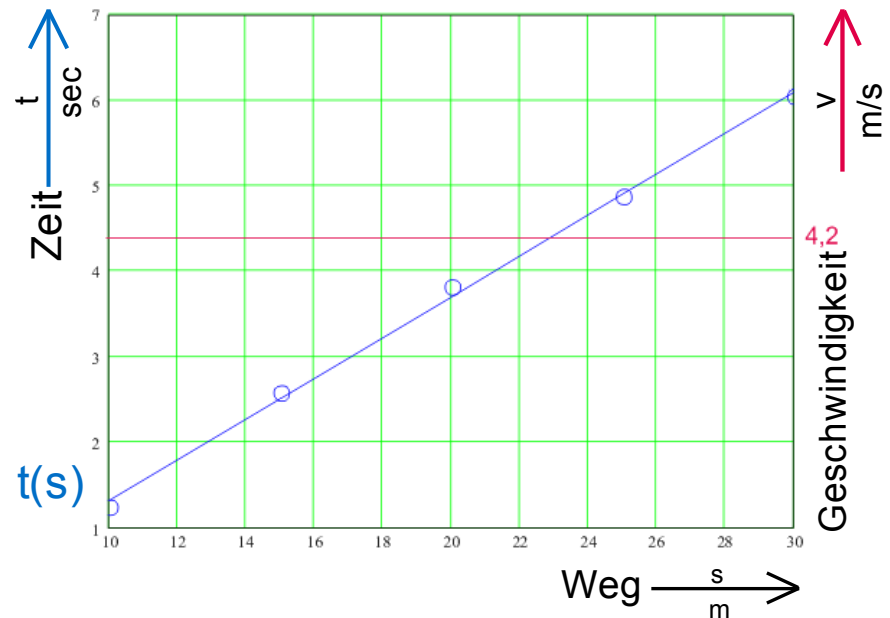


mit $v_{sl} = 4,2 \text{ m/sec}$:

$$c_{a_sl} = \frac{2 \cdot m \cdot g}{(v_{sl})^2 \cdot A_F \cdot \rho} = 0,94$$

→ Lift coefficient can be calculated

→ determination of coordinate point_1 on polar curve



Linking to School Physics

determination of operating point_1 on the polar curve:

$$c_{a_sl} = 0,94$$

inclusion of further drag coefficients:

$$c_{w_sl} = c_{wp_sl} + \frac{c_{a_sl}^2}{2 \cdot \pi \cdot \Lambda} + c_{ws}$$

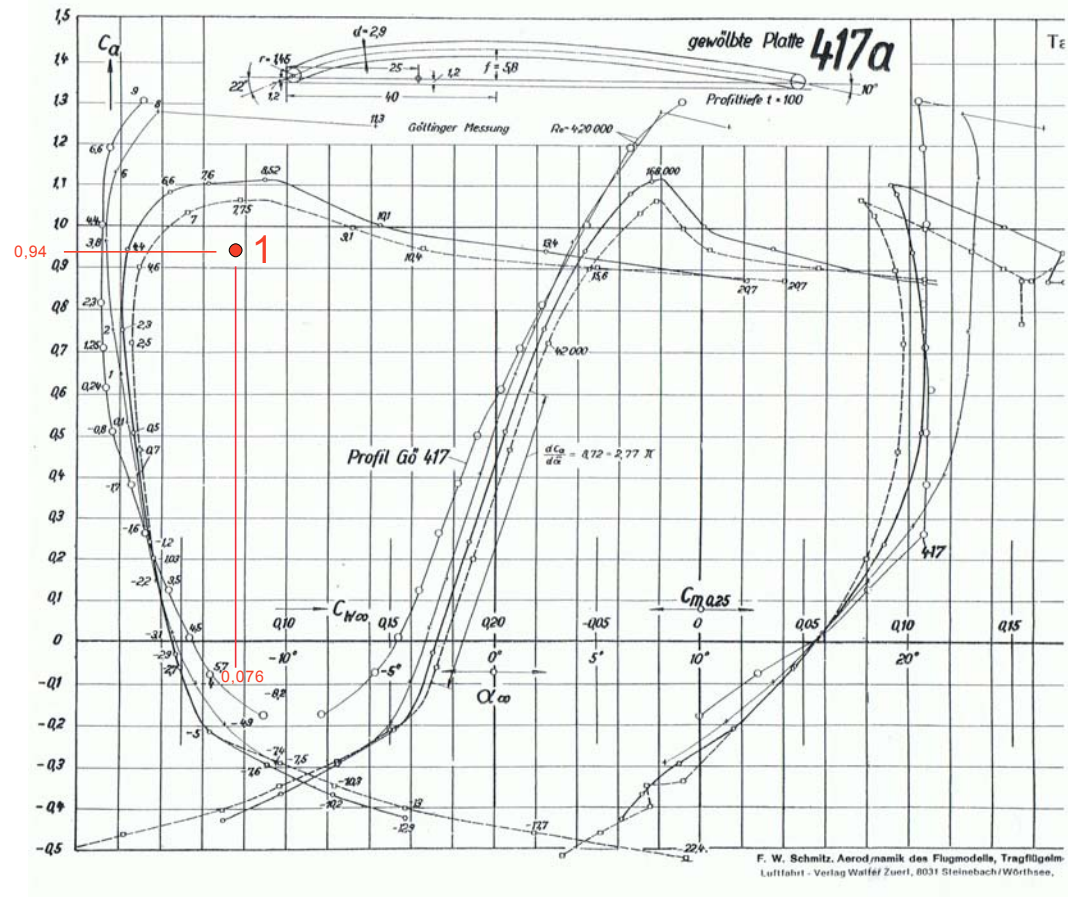
$$= 0,076$$

→ we determined the operating point_1

→ the Drag force is:

$$F_{w_sl} = \frac{\rho}{2} \cdot v_{sl}^2 \cdot c_{w_sl} \cdot A$$

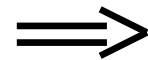
$$= 0,13N$$



Linking to School Physics

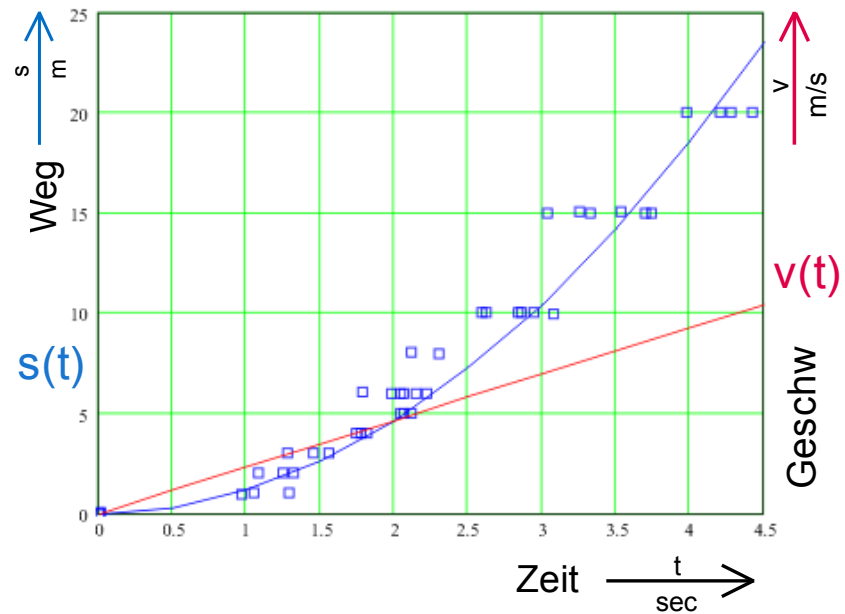
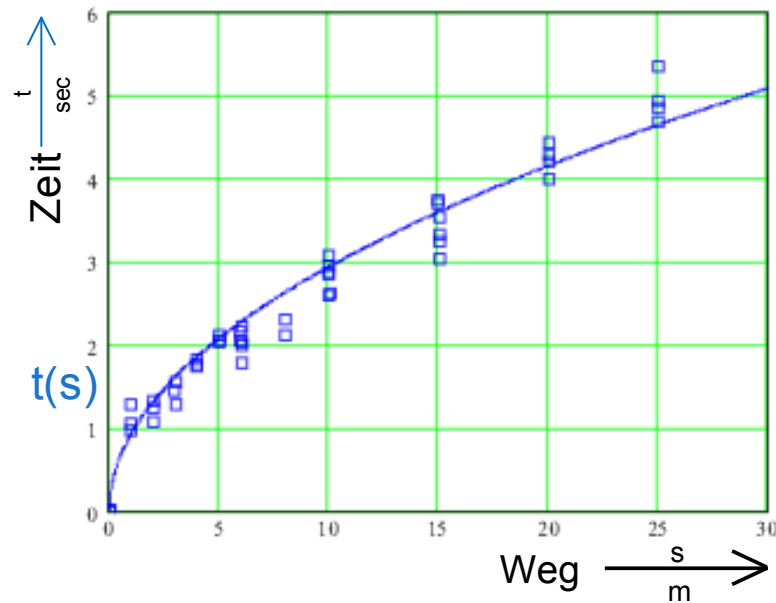
- take-off process: $v \neq \text{const}$,
- measurement of the accelerated phase over path marks with the help of pupils

measurement: $t = f(s)$



calculation: inverse funktion $s = g(t)$

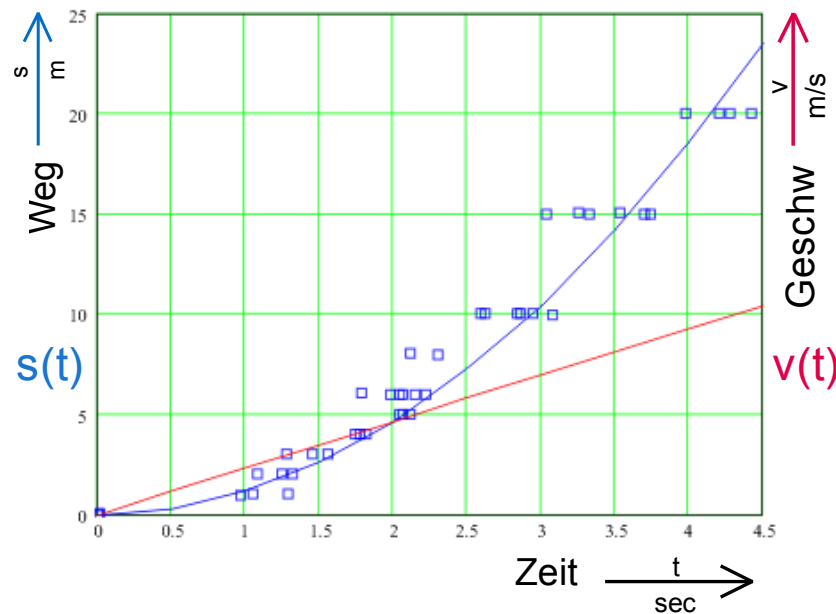
find out the value „a“ for acceleration: $s(t) = \frac{a}{2} \cdot t^2 \rightarrow$ interpolation trough the points



Linking to School Physics

- take-off process: $v \neq \text{const}$, calculation:

interpolation give the value for acceleration "a" in: $s(t) = \frac{a}{2} \cdot t^2$ $a = 2.3 \cdot \frac{\text{m}}{\text{s}^2}$



we get the thrust force
in acceleration phase:

$$F_{s_b} = m \cdot a$$

with mass $m = 0.17 \cdot \text{kg}$ $F_{s_b} = 0,4 \text{N}$

in comparison:

static thrust $F_{s_st} = 0.8 \text{N}$

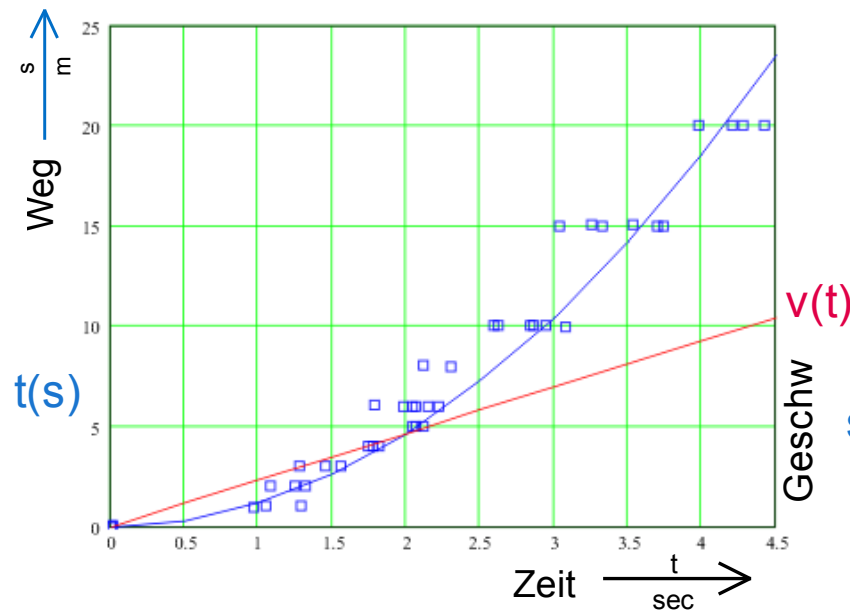
Linking to School Physics

- take-off process in total: from $v \neq \text{const}$ until $v = \text{const}$

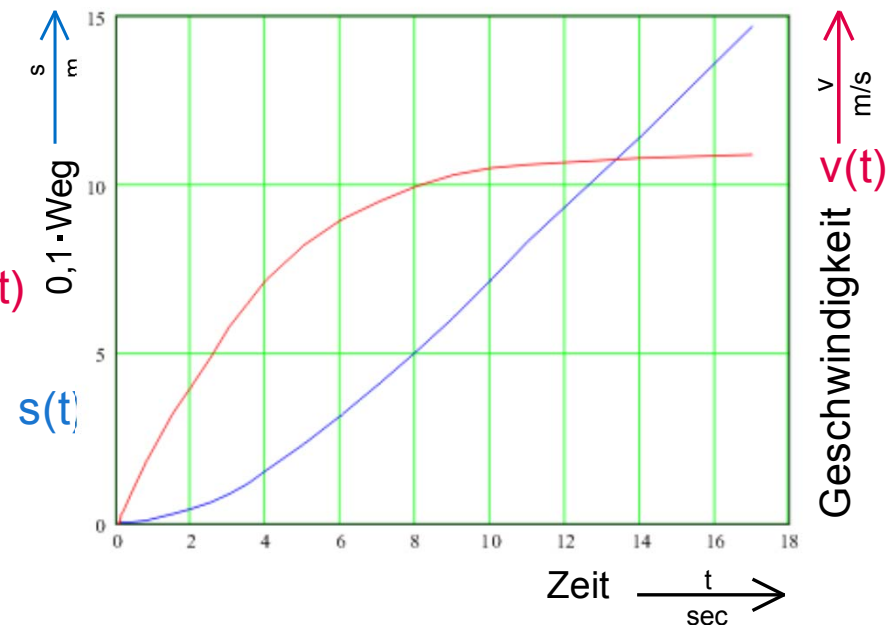
measurement: $t = f(s)$



calculation: solving DEQ = $g(t)$



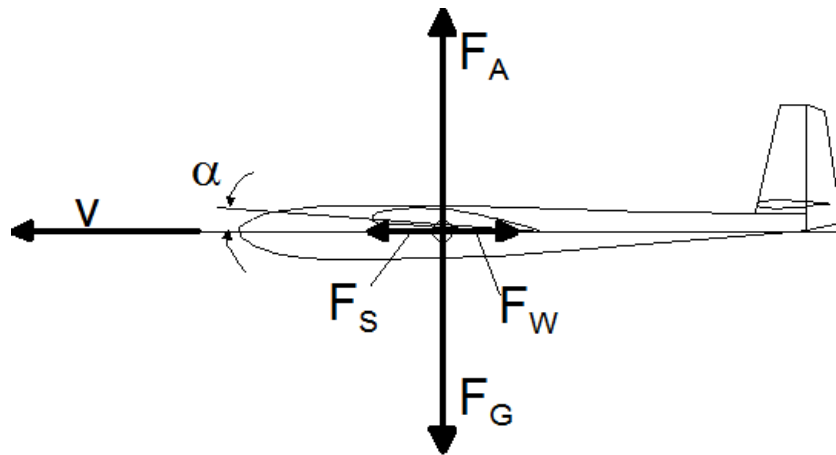
taking-off in the first seconds



taking-off until $v = \text{const}$ for $t \geq 12\text{sec}$

Linking to School Physics

- Cruising flight: $v = \text{const}$, measurement fast flight:

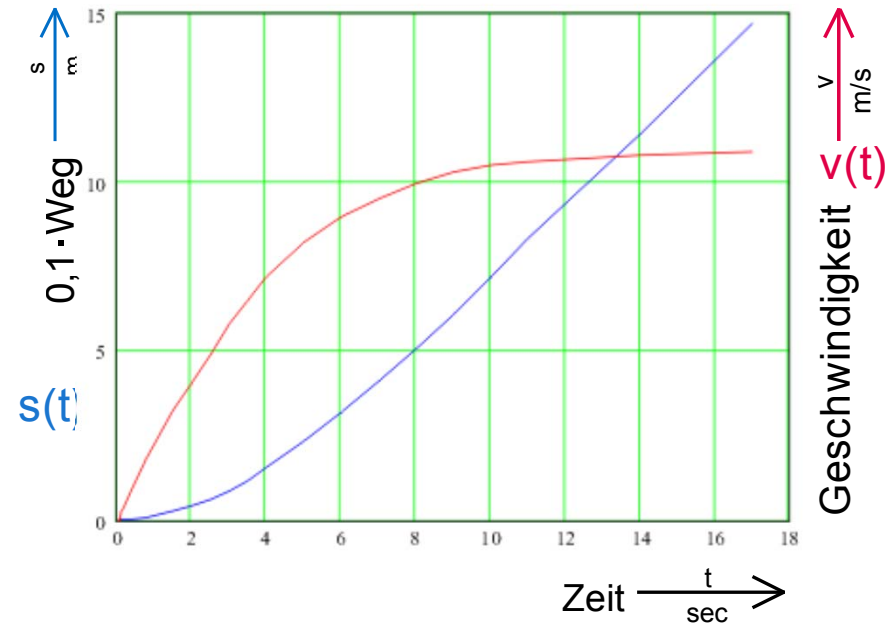


with $v_{fa}=11\text{m/sec}$:

$$c_{a_{fa}} = \frac{2 \cdot m \cdot g}{(v_{fa})^2 \cdot A_F \cdot \rho} = 0,13$$

→ Lift coefficient can be calculated

→ determination of coordinate point_2 on polar curve



Linking to School Physics

determination of operating point_2 on the polar curve:

$$c_{a_fa} = 0,13$$

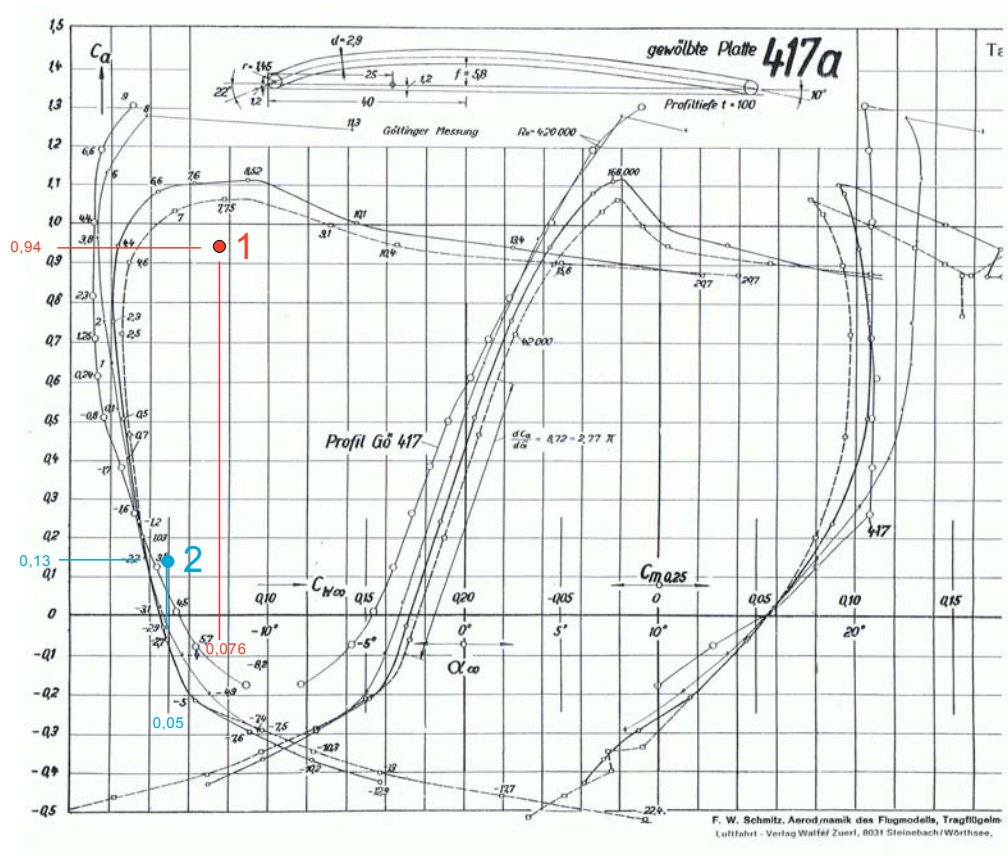
inclusion of further drag coefficients:

$$\begin{aligned} C_{w_fa} &= C_{wp_fa} + C_{ws} \\ &= 0,05 \end{aligned}$$

→we determined the operating point_2

the Drag force is:

$$\begin{aligned} F_{w_fa} &= \frac{\rho}{2} \cdot v_{fa}^2 \cdot c_{w_fa} \cdot A \\ &= 0,6N \end{aligned}$$



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Linking to School Physics

determine efficiency factor of propulsion, example fast flight

power output of the airscrew :

$$P_{mech_fa} = v_{fa} \cdot F_{S_fa} = 6,5W$$

electrical input:

$$P_{el} = U_{acc} \cdot I_{acc} = 21W$$

→ efficiency factor of driving system: $\eta_{ges_fa} = \frac{P_{mech_fa}}{P_{el_fa}} = 0,31$

breakdown in individual components:

controller

electric motor

propeller

$$\eta_{reg} = 0,95$$

$$\eta_{mot} = 0.85$$

$$\eta_{prop} = 0,4$$

Summary

On an example could be shown, that we model aircraft flyer have a good chance to recruit pupils for our club in cooperation with a school.

Indoor flying has been proven successful to learn remote control operating.

The cooperation allows the practical application of the teaching material in physics.